KD TECH

SSC JE PSU'S CENTRAL & STATE AE/JE 2007, OUTRAM LINES, 1ST FLOOR, NEAR GTB NAGAR METRO STATION, GATE NO. - 2, DELHI-110009

# **SSC JE CONVENTIONAL 2017**

### **GENERAL ENGINEERING (MECHANICAL)**

#### 1. (a) Define the following:

- (i) Reversible and Irreverasible process
- (ii) External and Internal irreversibility
- (iii) Intensive and Extensive properties

#### Solution :

[15 Marks]

(i) A reversible process is defined as a process that can be reversed without leaving any trace on the surroundings. That is, both the system and the sorroundings are returned to their initial states at the end of the reverse process. This is possible only if the net heat and net work exchange between the system and the surroundings is zero for the combined (original and reverse) process.

A reversible process is carried out infinitely slowly, every states of path are eqilibrium with surrounding.



But in Irreversible process every states carried by system are nonequilibrium. All spontanceous process are irreversible in nature.

(ii) A process is called internally reversible if no irreversibilities occur within the boundaries of the system during the process. During an internally reversible process, a system proceeds through a series of equilibrium state, and when the process is reversed, the system passes through exactly the same equilibrium states while returing to its initial state. The quasi-equilibrium process is an example of an internally reversible process.

A process is called externally reversible if no irreversibilities occur out side the system boundaries during the process. Heat transfer between a reservior and a system is an externally reversible process if the outer surface of the system is at the temperature of the reservoir.

A process is called totally reversible, or simply reversible, if it involves no irreversibilities within the system or its surroundings.

(iii) Any characteristic of a system is called a property. Properties are considered to be either intensive or extensive. Intensive properties are those that are independent of the mass of a system, such as temperature, pressure, and density. Extensive properties are those whose values depend on the size-or extent-of the system. Total mass, total volume, and total momentum are some examples of extensive properties.

#### (b) Describe the following:

- (i) Clausius Statement
- (ii) Kelvin-Planck Statement
- (iii) Perpetual motion machine of the second kind

#### Solution :

- Clausius states that,
- (i) It is impossible to construct a device that operates in a cycle and produces no effect other than the transfer of heat from a lower-temperature body to a higher-temperature body.















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- So  $P_m = \frac{2}{0.746}$ 
  - P\_= 1239.93 kPa
- P<sub>m</sub><sup>iii</sup>= 1.239 MPa or
- Explain the effect of Super heating and Sub-cooling on vapour compression refrigeration (C) cvcle.

#### Solution:

Superheating of the suction vapour is advisable in practive because it ensures complete vaporization of the liquid in the evaporator before it enters the compressor. The effect of superheating of the vapour as follows:

- Increase in specific volume of suction vapour from  $v_1$  to  $v'_1$ . Thus increase in (i) volumetric efficiency.
- Increase in refrigerating effect. (ii)
- (iii) Increase in specific work.



Subcooling- It is possible to reduce the temperature of the liquid refrigerant to within a few degrees of the temperature of the water entering the condenser in some condenser designs by installing a subcooler, between the condenser and the expansion valve. The effect of subcooling of the liquid.

It will be seen that subcooling reduces flashing of the liquid during expansion and increases the refrigerating effect. Consequently, the piston displacement and horsepower per ton are reduced for all refrigerants.



- (d) An air standard Brayton cycle has air entering the compressor at 100 kPa and 27°C. The pressure ratio is 10 and the maximum allowable temperature in the cycle is 1350 **K.** Determine
  - (i) temperatures at salient points of the cycle
  - compressor and turbine work per unit mass of air (ii)
  - (iii) net work output and work ratio
  - (iv) thermal efficiency of the cycle
  - specific air consumption in kg/kWh (v)
  - Improvement in the thermal efficiency of the cycle if a regenerator with 100% (vi) effectiveness is incorporated in the cycle.

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In reverse polarity, the electrode is positive, and deeper weld penetration is possible. The SMAW process is commonly used in general construction, in shipbuilding, on pipelines, and for maintenance work, because the equipment is portable and can be easily maintained.

#### (c) Explain the different operations performed in grinding machine.

#### Solution:

The basic types of grinding operations surface, cylindrical, internal, and centerless grinding

#### (i) Surface Grinding-

Surface grinding involves grinding flat surfaces and is one of the most common grinding operations.

A straight wheel is mounted on the horizontal spindle of the grinder. Traverse grinding occurs as the table reciprocates longitudinally and feeds laterally after each stroke. In plunge grinding, the wheel is moved radially into the workpiece, as it is when grinding a groove.



#### (ii) Cylindrical Grinding

In cylindrical grinding, also called center-type grinding external cylindrical surfaces and shoulders of the workpiece are ground.

The roatating cylindrical workpiece reciprocates laterally along its axis. In grinders used for large and long workpieces, the grinding wheel reciprocates; called a roll grinder. The workpiece in cylindrical grinding is held between centers or in a chuck. For straight cylindrical surfaces, the axes of rotation of the wheel and workpiece are parallel.



#### (iii) Internal Grinding

In internal grinding a small wheel is used to grind the inside diameter of the part, such as to bushings and bearing races. The workpiece is held in a rotating chuck and the wheel rotates at 30,000 rpm or higher. Internal profiles can also be ground with profile dressed wheels that move radially into the workpiece.





## (d) Mention the differences between shaper and planer machine tools. Solution:

**Planing** is a relatively simple cutting operation by which flat surfaces, as well as various cross sections with grooves and notches, are produced along the lenght of the workpiece. Planing is usually done on large workpieces.

In a planer, the workpiece is mounted on a table that travels along a straight path. A horizontal cross-rail, which can be moved vertically along the ways in the column, is equipped with one or more tool heads.

Because of the reciprocating motion of the workpiece, elapsed noncutting time during the return stroke is significant.Cutting speed in planer can range up to 120 m/min.

**Shaping** is used to machine parts; it is much like planing, except that the parts are smaller and Cutting by shaping is basically the same as by planing. In a horizontal shaper, the tool travels along a straight path, and the workpiece is stationary. The cutting tool is attached to the tool head, which is mounted on the ram.

The ram has a reciprocating motion, and in most machines, cutting is done during the forward movement of the ram.

#### 5. (a) Give the classification of kinematic pairs.

#### Solution:

The kinematic pairs may be classified according to the following considerations; according to the type of relative motion between the elements:

(i) **Sliding pair:** When the two elements of a pair are connected in such a way that one can only slide relative to the other. Example-piston and cylinder, cross-head and guides of a reciprocatings team engine.

(ii) **Turning pair:** When the two elements of a pair are connected in such a way that one can only turn or revolve about a fixed axis of another link. Example- Shaft with collars at both ends fitted into a circular hole, the crankshaft in a journal bearing in an engine.

(iii) **Rolling pair:** When the two elements of a pair are connected in such a way that one rolls over another fixed link. Example-Ball and roller bearings.

(iv) Screw pair: When the two elements of a pair are connected in such a way that one element can turn about the other by screw threads. Example-Lead screw of a lathe with nut, and bolt with a nut.

(v) Spherical pair: When the two elements of a pair are connected in such a way that one element turns or swivels about the other fixed element, the pair formed is called a spherical pair. Example-Ball and socket joint, attachment of a car mirror, pen stand etc.

### According to the type of contact between the elements:

(i) **Lower pair:** When the two elements of a pair have a surface contact when relative motion takes place and the surface of one element slides over the surface of the other. It will be seen that sliding pair turning pairs and screw pairs form lower pairs.



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**(ii) Higher pair:** When the two elements of a pair have a line or point contact when relative motion takes place and the motion between the two elements is partly turning and partly sliding.

Example- A pair of friction discs, toothed gearing, belt and rope drives, ball and roller bearings and cam and follower.

#### According to the type of closure:

(i) Self closed pair: When the two elements of a pair are connected together mechanically in such a way that only required kind of relative motion occurs, it is then known as self closed pair. The lower pairs are self closed pair.

(ii) **Force-closed pair:** When the two elements of a pairs are not connected mechanically but are kept in contact by the action of external forces, the pair is said to be a force-closed pair. The cam and follower is an example of force closed pair, as it is kept in contact by the forces exerted by spring and gravity.

(b) An engine, running at 150 r.p.m., drives a line shaft by means of a belt. The engine pulley is 750 mm diameter and the pulley on the line shaft being 450 mm. A 900 mm diameter pulley on the line shaft drives a 150 mm diameter pulley keyed to a dynamo shaft. Calculate the speed of the dynamo shaft, when (i) there is no slip, and (ii) there is a slip of 2% at each drive.



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$$\tau = \frac{R\theta}{l}G.$$
$$\frac{\tau_r}{r} = \frac{\tau}{R} = \frac{G\theta}{l}$$

The shear stress in torsion is linear function of radius of the shaft.

(d) Derive the expression for circumferential stress in a thin cylindrical vessel. Solution:

A thin cylindrical shell whose internal diameter is d, the thickness of the shell being t. Let the length of the shell be l. Let the shell be subjected to an internal pressure of intensity P.



Let us consider a longitudinal section XX through the axis, dividing the shell into two halves A and B. Now let us consider two elementary strips subtending an angle  $d\theta$  at the centre at an angle  $\theta$  on either side of the vertical through the centre.

Normal force on each strip  $dp_n = p r d\theta l$ , where r = radius of the shell.

The resultant of the two normal forces on the two elemental strips =  $dP = 2 pr l d\theta \cos \theta$  acting vertically, i.e. normal to XX.

Total force normal to XX on one side of XX = P

$$P = \int_{0}^{\pi/2} 2prl\cos\theta \,d\theta$$

 $= 2prl = pdl \qquad \dots \dots \dots \dots (i)$ 

p is intensity of radial pressure and *dl* is projected area

Let  $\sigma_c$  intensity of tensile stress induced in the metal across the section XX.

Resisting force =  $\sigma_c \times 2lt$ 

equating to equation (i)

 $\sigma_c \times 2lt = pdl$ 



This is the circumferential stress developed in the thin cylindrical pressure vessel due to internal pressure 'p'.